Model E.V.A.-1

Electronic Valve Actuator RESEARCH® CONTROL Valves

Technical Brief

DESCRIPTION

The Model EVA-1 is a small, electronically controlled, valve actuator developed specifically to fit 1/4 inch to 1 inch Research Control® Valves. Its accurate positioning and compact size make it especially suited to flow control in research and small process applications. The unit features:

- Microprocessor-controlled, linear stepper motor
- 4-20 mA analog input
- Position 4-20 mA analog output (optional)
- · Choice of 12 speeds
- Up to 40 pounds of stem thrust
- · Accurate and repeatable positioning
- Adjustable split range
- Quick and simple zero and span input and output adjustments
- Adjustable stroke from 0.1875" to 0.5625"
- · User adjustable direct or reverse action
- Optional handheld plug-in Communicator for all adjustments without removing the cover
- Controlled seating force to prevent innervalve damage
- Built-in temperature compensation
- Stainless steel yoke and rugged epoxy coated aluminum housing
- 115VAC/12VDC, 230VAC/12VDC, and 24VDC models available

OPERATION

The Model EVA-1 consists of a microprocessor-controlled, linear stepper motor that responds to an input signal of 4-20 mA DC. It also offers an optional isolated loop powered 4-20 mA position output for signaling back to an indicator or control panel. The standard Model EVA-1 requires a 115 VAC power supply with 230VAC and 24VDC models available. A stroke of 0.437 inches for the 1/4" unit or a stroke of 0.562 inches for the 1/2" to 1" units is standard and can be adjusted quickly and easily with two switches under the actuator cover or via the communication port. This ease of calibration can be used to split range the input or limit the up or down travel of the valve. The Unit utilizes a "dual speed" operating mode. The low speed mode generates high thrust for seating the valve and overcoming packing friction while the high speed mode allows the valve to respond quickly to large input signal changes.

RATINGS

NEMA 4: Watertight

EXPLOSION PROOF*: Class 1, Division 1, Group C & D

*Standard models approved by FM and CSA.



Shown mounted on Type 807 valve assembly

SPECIFICATIONS

Electrical:

Supply Power/Standard:

115 VAC +/- 10% @ 50-60 Hz and/or 12 VDC

Supply Power/Optional:

230 VAC +/- 10% @ 50-60 Hz and/or 12 VDC

24 VDC +/- 3%

Control input: 4-20 mA DC @ 125 ohms

Position Output: 4-20 mA DC isolated, 0-800

ohm loop impedance

Mechanical:

Stroke Length: up to 0.562" (adjustable)
Thrust: 40 lbs. at minimum step rate; 10 lbs.

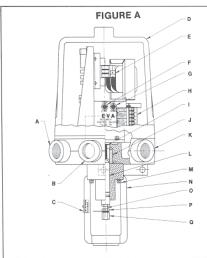
at maximum step rate

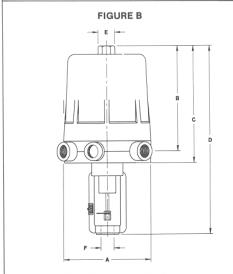
(See Output vs. Speed Chart on page 2)

Height: 13 inches (actuator with yoke only)
Weight: 12 lbs. (actuator with yoke only)
Operating Temperature Range: -10° to +60° C









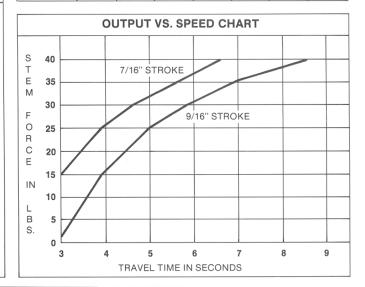
Description of items

- A. Setup/service port (1/2" NPT)
- B. Signal port (1/2" NPT)
- C. Travel scale
- D. Cover
- E. Input terminal block (4-20mA)
- F. Span/zero switch
- G. Travel switch
- H. Power supply board
- I. Motor shaft

Description of items

- J. Anti-rotation sleeve
- K. Supply power port (1/2" NPT)
 L. Spring loaded stem assembly
- Spring loaded ste
 M. Cap screw
- IVI. Cap scre
- N. Yoke
- O. Actuator stem connector
- P. Travel pointer locknut
- Q. Trim stem connector

VALVE SIZE	DIMENSIONS (in inches)						
	Α	В	С	D	E	F	STROKE
1/4"	6.0	6.75	7.0	12.37	1.13 HEX	0.625	0.437
1/2", 3/4", 1"	6.0	6.75	7.0	12.37	1.13 HEX	0.875	0.562

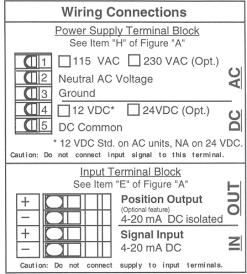


Calibration Procedure

- 1) Input Zero: With P1 Jumper set to the "Normal" position, apply input signal for the "Closed " valve position. Use the UP/DOWN switch to close the valve. Push the SPAN/ZERO switch to ZERO.
- 2) Input Span: Apply input signal for the "Open " valve position. Use the UP/DOWN switch to open the valve. Push the SPAN/ZERO switch to SPAN.
- 3) Output Zero*: Apply input signal for the "Closed " valve position. Move P1 Jumper to the Zero position. Adjust the output to read 4 mA with the UP/DOWN switch. Push the SPAN/ZERO switch to ZERO.
- 4) Output Span*: Apply input signal for the "Open " valve position. Move P1 Jumper to the Span position. Adjust the output to read 20 mA with the UP/DOWN switch. Push the SPAN/ZERO switch to Span.
- 5) Return P1 Jumper to the Normal position.

Note: P1 is located on the electronic logic card. * Optional feature

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Normal	Zero	Span			
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